

JP3 series



Product Segments

Industrial Motion

TiMOTION's JP3 series inline linear actuator was designed for low load industrial applications where up to IP69K dust and liquid ingress protection is necessary. It is best suited for applications with visual or compact installation dimension requirements. Hall sensors are optional for the JP3 which allow for synchronization and position feedback.

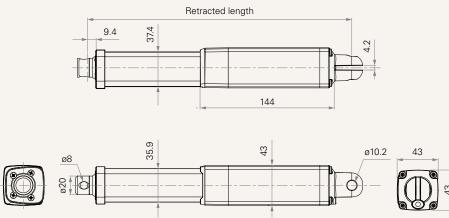
General Features

Max. load	2,000N (push/pull)
Max. speed at max. load	3.5mm/s
Max. speed at no load	23.5mm/s
Retracted length	≥ Stroke + 217mm
IP rating	IP69K
Certificate	UL73
Stroke	20~1000mm
Output signals	NPN Hall sensors
Voltage	12/24V DC; 12/24V DC (PTC)
Color	Black, grey
Operational temperature range	-5°C~+65°C
Operational temperature range	+5°C~+45°C
at full performance	
Storage temperature range	-40°C~+70°C

JP3 series

Drawing

Standard Dimensions (mm)



Load and Speed

CODE	Load (N)	Load (N)						peed (mm/s)Typical Current (A)			Typical Speed (mm/s)	
	Push	Pull	Locking Force (N)	No Load 24V DC	With Load 24V DC	d No Load 24V DC	With Loa 24V DC	d No Load 12V DC	With Loa 12V DC	d No Load 12V DC	With Load 12V DC	
Motor Speed (5600RPM, Duty Cycle 20% : 2min on / 8min off)												
В	2000	2000	2000	1.5	3.3	7.0	4.5	2.5	6.5	7.0	3.5	
C	1500	1500	1000	1.5	3.3	10.0	6.5	2.5	6.5	10.0	6.5	
D	1000	1000	700	1.5	3.0	14.5	9.8	2.5	6.0	14.5	8.5	
E	500	500	500	1.5	3.0	23.5	19.0	2.5	6.0	23.5	19.0	

Note

1 Please refer to the approved drawing for the final authentic value.

- 2 This self-locking force level is reached only when a short circuit is applied on the terminals of the motor. All the TiMOTION control boxes have this feature built-in. The self-locking force is a minimum value and can be actually higher.
- 3 The current & speed in table are tested with 24V DC motor. With a 12V DC motor, the current is approximately twice the current measured in 24V DC; speed will be similar for both voltages.
- 4 The current & speed in table are tested when the actuator is extending under push load.
- 5 The current & speed in table and diagram are tested with a stable 24V DC power supply.
- 6 Without load, noise level ≤ 65dBA (by TiMOTION test standard, ambient noise level ≤ 36dBA)
- 7 Standard stroke: Min. ≥ 20mm, Max. please refer to below table

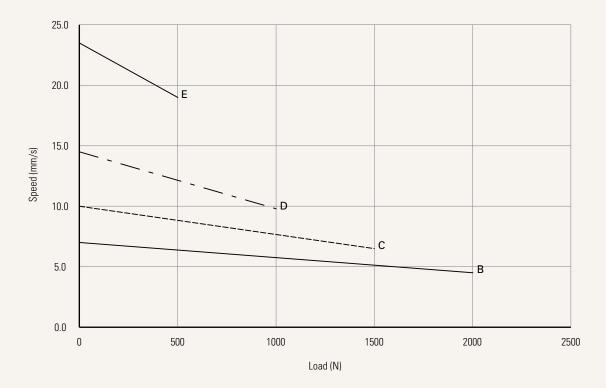
CODE	Load (N)	Max Stroke (mm)
В	2000	500
C	1500	600
D	1000	800
E	500	1000





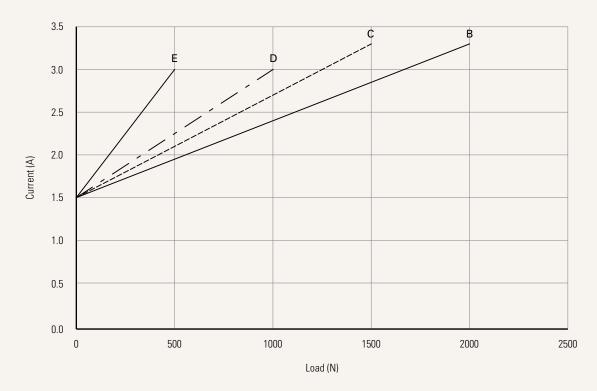
Performance Data (24V DC Motor)

Motor Speed (5600RPM, Duty Cycle 20%: 2min on / 8min off)



Speed vs. Load

Current vs. Load

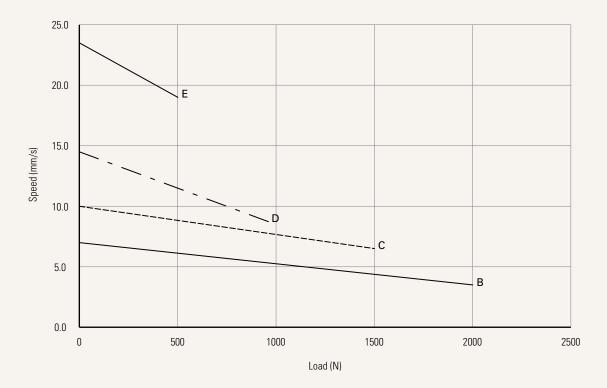






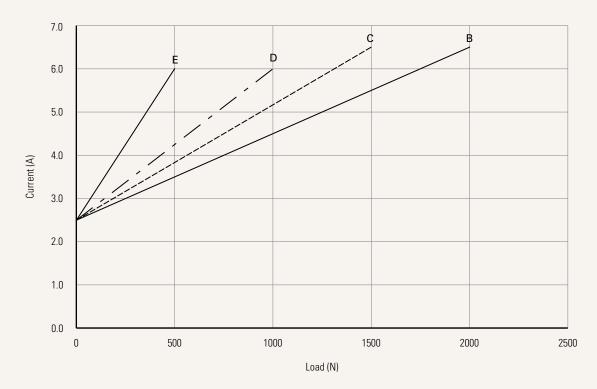
Performance Data (12V DC Motor)

Motor Speed (5600RPM, Duty Cycle 20%: 2min on / 8min off)



Speed vs. Load

Current vs. Load





JP3 Ordering Key

1 T*i* MOTION

Version: 20240528-I

JP3	
	Voltage
	<u>See page 9</u>
	Load and Speed
	Stroke (mm)
	Retracted Length (mm)
	Rear Attachment

Voltage See page 9	1 = 12V DC	2 = 24V DC	5 = 24V DC, PTC	6 = 12V DC, PTC				
Load and Speed	<u>See page 2</u>							
Stroke (mm)	<u>See page 2</u>							
Retracted Length (mm)	<u>See page 6</u>							
Rear Attachment (mm) <u>See page 7</u>	1 = Aluminum, U clevis,	slot 4.2, depth 18.0, hole 10.	2					
Front Attachment (mm) <u>See page 7</u>	1 = Aluminum, slotless, hole 6.4 2 = Aluminum, slotless, hole 8.0 3 = Aluminum, U clevis, slot 6.0, depth 13.0, hole 10.0 4 = Aluminum, U clevis, slot 6.0, depth 13.0, hole 6.4 5 = Aluminum, U clevis, slot 6.0, depth 13.0, hole 8.0 6 = Aluminum, hole 10.0							
Direction of Rear Attachment (Counterclockwise) See page 8	1 = 0°							
Color	1 = Black	2 = Pantone 428C						
IP Rating	1 = Without 2 = IP54	3 = IP66 5 = IP66W	6 = IP66M 7 = IP68	8 = IP69K				
Special Function of Spindle Subassembly	0 = Without (Standard)							
Function of Limit Switches See page 8	 1 = Two micro switches cut off the actuator at end of stroke 2 = Two micro switches cut off the actuator at end of stroke + third one in between sends signal 3 = Two micro switches send signal at end of stroke 4 = Two micro switches send signal at end of stroke + third one in between sends signal 							
Output Signal	0 = Without	N = NPN Hall sensor *	2					
Connector See page 8	1 = DIN 6P, 90° plug	2 = Tinned leads						
Cable Length (mm)	0 = Straight, 100	1 = Straight, 500	3 = Straight, 1000					



Retracted Length (mm)

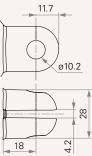
- 1. Calculate A+B+C = Y
- 2. Retracted length needs to \geq Stroke + Y

A. Front Atta	chment	A. Front Attachment		put Signal
, 2, 6	+217		0	-
3, 4, 5	+230		N	+13
B. Stroke (m	m)			
20~150	-			
151~200	-			
201~250	+5			
251~300	+10			
301~350	+15			
351~400	+20			
401~450	+25			
451~500	+30			
501~550	+35			
551~600	+40			
601~650	+45			
651~700	+50			
701~750	+55			
751~800	+60			
801~850	+65			
851~900	+70			
901~950	+75			
951~1000	+80			



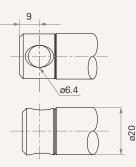
Rear Attachment (mm)

1 = Aluminum, U clevis, slot 4.2, depth 18.0, hole 10.2

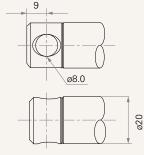


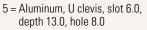
Front Attachment (mm)

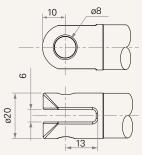
1 = Aluminum, slotless, hole 6.4



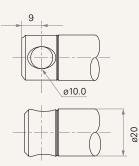
2 = Aluminum, slotless, hole 8.0



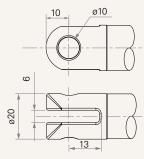




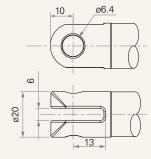
6 = Aluminum, hole 10.0



3 = Aluminum, U clevis, slot 6.0, depth 13.0, hole 10.0



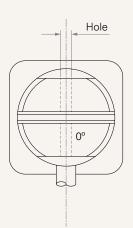
4 = Aluminum, U clevis, slot 6.0, depth 13.0, hole 6.4





Direction of Rear Attachment (Counterclockwise)

1 = 0°

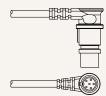


Functions for Limit Switches

Wire Definitions									
CODE	Pin								
	🔵 1 (Green)	🛑 2 (Red)	🔵 3 (White)	4 (Black)	😑 5 (Yellow)	6 (Blue)			
1	extend (VDC+)	N/A	N/A	N/A	retract (VDC+)	N/A			
2	extend (VDC+)	N/A	middle switch pin B	middle switch pin A	retract (VDC+)	N/A			
3	extend (VDC+)	common	upper limit switch	N/A	retract (VDC+)	lower limit switch			
4	extend (VDC+)	common	upper limit switch	medium limit switch	retract (VDC+)	lower limit switch			

Connector

 $1 = \text{DIN 6P}, 90^{\circ} \text{ plug}$



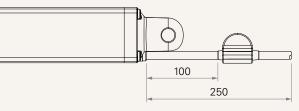
2 = Tinned leads





Voltage

5 = 24V DC, PTC



PTC outside the motor; at cable length 100mm, min total cable = 250mm

Terms of Use

The user is responsible for determining the suitability of TiMOTION products for a specific application. TiMOTION products are subject to change without prior notice.